

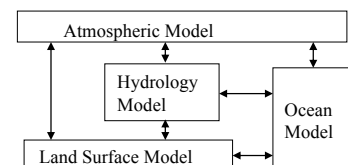
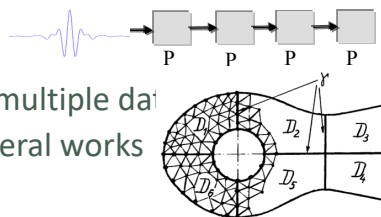
Parallel Computing with MPI

Module HPC - ED SPI 2018-2019

Présentée par Jian-Jin Li

Introduction – Parallel computing & Parallelism

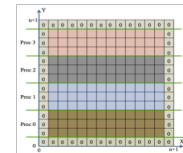
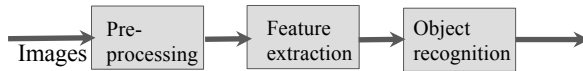
- Parallel computing
 - Solve larger problem in less time in using concurrent processes/threads
- Parallelism
 - Parallelism refers to the simultaneous occurrence of events on a computer
 - Levels of parallelism: bit-level, instruction-level, **task-level**, job-level
- Sources of parallelism
 - Work in pipeline
 - Repeat one action on multiple data
 - Do simultaneously several works



Introduction - Parallel architectures

- Classification of Flynn

- SISD: 1 instruction works on 1 data; serial computer $a \times b = a \times b$
- SIMD: 1 instruction works on multiple data; vector processor, processor array, GPU $X + Y = \begin{matrix} x_0 + y_0 \\ \dots \\ x_3 + y_3 \end{matrix}$
- MISD: multiple instructions work in pipeline
- MIMD: multiple instructions work asynchronously on multiple data



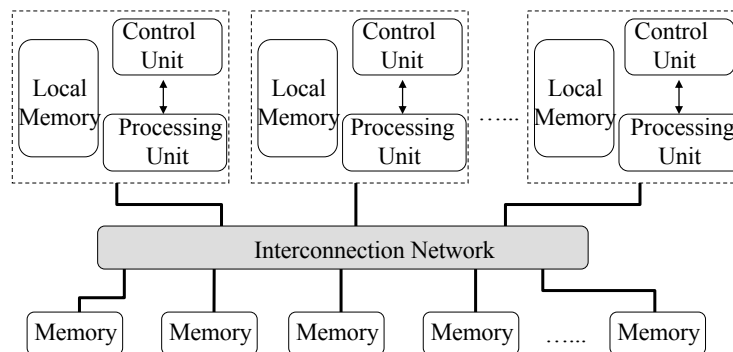
Introduction - Parallel architectures

- MIMD - Characteristics

- Asynchronous operation on multiple processors
- Communication way: Shared or Distributed memory

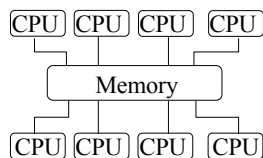
Introduction - Parallel architectures

- Shared Memory MIMD
 - Communication way: shared memory

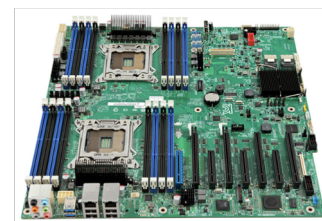


Introduction - Parallel architectures

- Shared Memory MIMD
 - SMP (Symmetric Multi-Processor)
 - Identical processors (2-128)
 - UMA / NUMA



node27&29:
E5-2670 2.60GHz

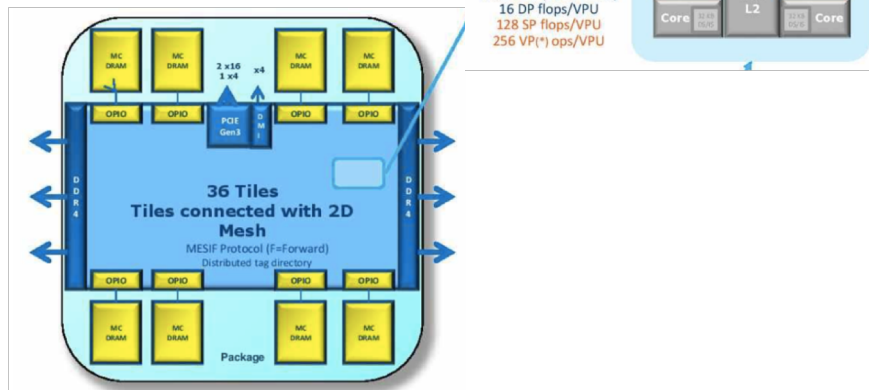


Multi Xeon motherboard

- Multi-sockets server

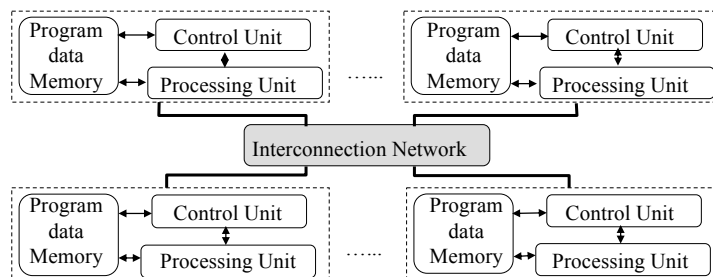
Introduction - Parallel architectures

- SMP - example
 - Intel Xeon Phi 72 cores



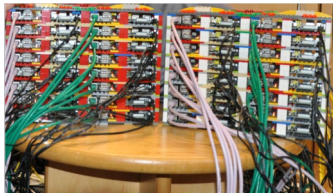
Introduction - Parallel architectures

- Distributed Memory MIMD
 - Communication way: message passing



Introduction - Parallel architectures

- Distributed Memory MIMD - Cluster
 - Collection of computers interconnected by :
 - a local network (Gigabit Ethernet)
 - or a dedicated interconnection network (infiniband)
 - Slower inter-processors communication
 - Distributed computing



Raspberry Pi – University of Southampton



Beowulf project – NASA 1994



Cluster LIMOS

Introduction - Parallel architectures

- TOP 500 Supercomputer

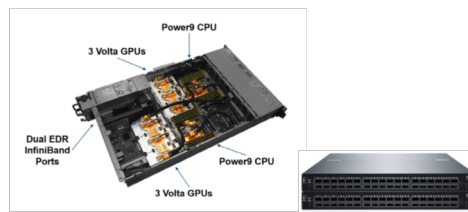
Rank	System	Cores	Rmax (TFlop/s)	Rpeak (TFlop/s)	Power (kW)
1	Summit - IBM Power System AC922, IBM POWER9 22C 3.07GHz, NVIDIA Volta GV100, Dual-rail Mellanox EDR Infiniband , IBM DOE/SC/Oak Ridge National Laboratory United States	2,397,824	143,500.0	200,794.9	9,783
2	Sierra - IBM Power System S922LC, IBM POWER9 22C 3.1GHz, NVIDIA Volta GV100, Dual-rail Mellanox EDR Infiniband , IBM / NVIDIA / Mellanox DOE/NNSA/LLNL United States	1,572,480	94,640.0	125,712.0	7,438
3	Sunway TaihuLight - Sunway MPP, Sunway SW26010 260C 1.45GHz, Sunway , NRCP National Supercomputing Center in Wuxi China	10,649,600	93,014.6	125,435.9	15,371
4	Tianhe-2A - TH-IVB-FEP Cluster, Intel Xeon E5-2692v2 12C 2.2GHz, TH Express-2, Matrix-2000 , NUDT National Super Computer Center in Guangzhou China	4,981,760	61,444.5	100,678.7	18,482
5	Piz Daint - Cray XC50, Xeon E5-2690v3 12C 2.6GHz, Aries interconnect , NVIDIA Tesla P100 , Cray Inc. Swiss National Supercomputing Centre (CSCS) Switzerland	387,872	21,230.0	27,154.3	2,384

Introduction - Parallel architectures

- Summit (IBM) – DOE/SC/ORNL (USA) (N^o 1 – Nov. 2018)



256 cabinets, 18 nodes per cabinet
=> 4608 nodes



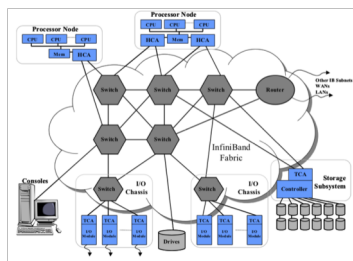
1 node:
2 IBM Power9 CPU (22 cores)
6 NVIDIA V100 GPU (640 cores)



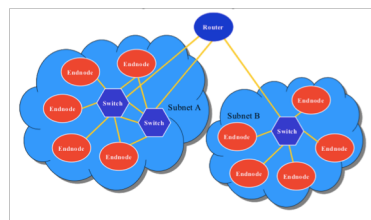
Source: ORNL – Mellanox Technologies

Introduction - Parallel architectures

- Summit
 - Connection between nodes: Mellanox dual-rail EDR 100Gb/s IB
 - Connection between CPUs and GPUs: NVLink



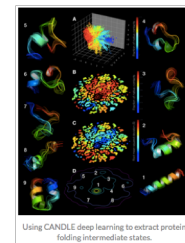
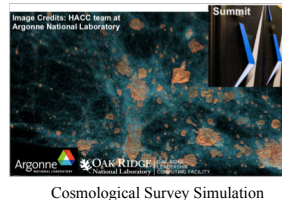
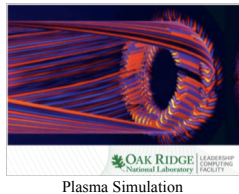
InfiniBand Fabric



(source: Mellanox Technologies)

Introduction - Parallel architectures

- Summit
 - Software
 - OS: RHEL 7.4; Compiler: XLC 13.1, nvcc 9.2
 - Math Lib.: ESSL, CUBLAS 9.2; MPI: Spectrum MPI
 - AI software: PowerAI DDL
 - Applications



Cancer Surveillance
Source : National Cancer Institute

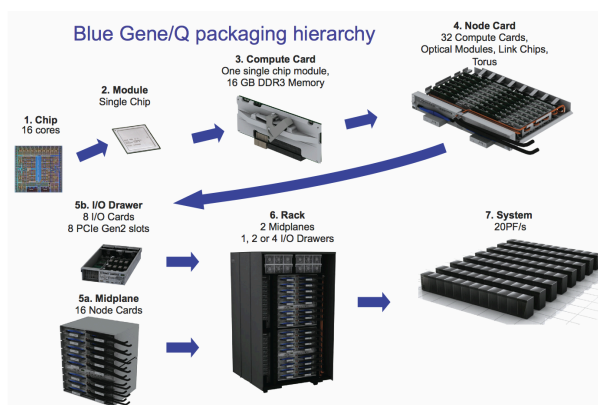
Introduction - Parallel architectures

- Sequoia (IBM) – DOE/NNSA/ ORNL (USA) (N° 1 – June 2012)
 - BlueGene/Q system
 - Soc custom
 - chip → module → node → rack → system
 - IBM Power BQC, 1 572 864 cores
 - Network
 - 5D torus + Control network



Introduction - Parallel architectures

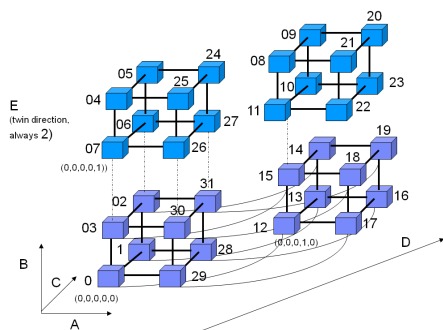
- Sequoia - BlueGene/Q
 - SoC based



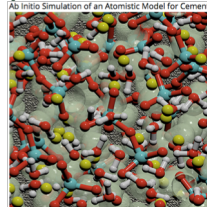
Source: LLNL, USA

Introduction - Parallel architectures

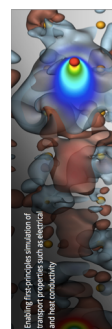
- Sequoia - BlueGene/Q
 - 5D torus
- 
- The diagram illustrates a 5D torus network topology. It consists of two parts: a small 2D section on the left and a larger 3D section on the right. The nodes are represented by blue cubes. In the 2D section, nodes are labeled 04, 05, 24, and 25, connected in a square. In the 3D section, nodes are labeled 08, 09, 10, 11, 20, 21, 22, and 23, arranged in a more complex grid-like structure with multiple connections between them.
- Softwares
 - Linux environment: Fortran, C, C++, MPI, OpenMP, ESSL
 - Applications
- 
- A small, low-resolution image showing a 3D molecular model, likely a protein structure, rendered in shades of blue and white. It appears to be a close-up of a specific part of the molecule.



Source: IDRIS, France



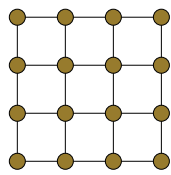
Code: Qbox
Machine: ASC Sequoia Initial Delivery System (Dawn)
Processors: 32,768
Run time: 30 hours
Visualization: Liam Krauss
Contact: Erik Draege



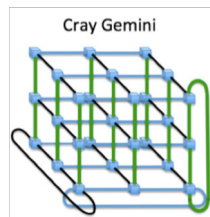
Source: LLNL

Interconnection Networks - Direct network

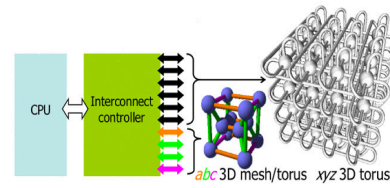
- Direct networks



2D Mesh



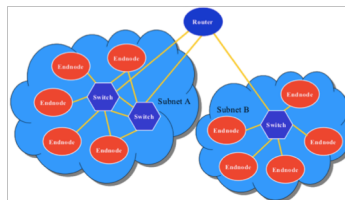
Cray Gemini 3D Torus, Titan
Source: ORNL, USA



Source: AICS, Kobe, Japan

- Indirect networks

- Fat tree (Summit – ORNL/USA)



Interconnection Networks - Direct network

- Basic properties: Topology

- *Node degree*: number of channels connecting this node to its neighbors
- *Diameter*: the maximum distance between two nodes in the network
- *Regularity*: all the nodes of a network have the same degree
- *Symmetry*: a network looks alike from every node

- “Good” properties of interconnection network

- Performance: low diameter, low latency, high bandwidth
- Programming facility: regularity, scalability

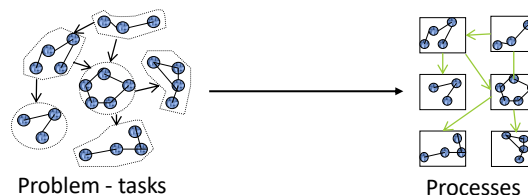
Programming MIMD architecture

- Programmers must use threads or processes
- Spread the workload across multiple cores
- Write parallel algorithms
 - Easy and quick parallel programming
 - Parallelization with compiler
 - Limitation of processors number
 - Programming library: OpenMP, pthread, TBB
 - Very-large number of processors
 - Parallel programming difficult
 - Programming library: MPI
 - Hybrid programming: MPI for DM nodes & OpenMP/TBB/GP for SM cores

DM – Distribute Memory
SM – Shared Memory

MPI - MPI Programming Model

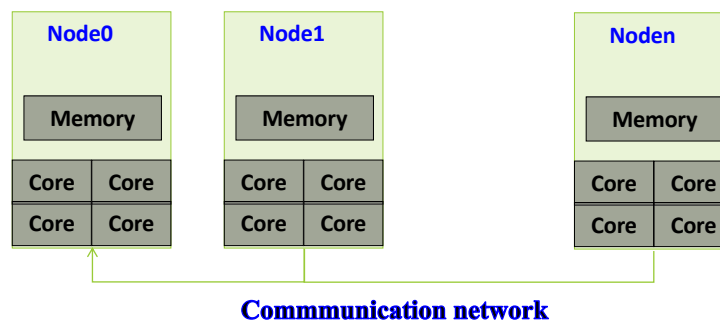
- Group of processes to solve **together** a problem



- New issues
 - Parallel tasks identification; problem decomposition
 - Tasks synchronization, communication, optimization
 - New bug types (deadlock, interference), starvation...

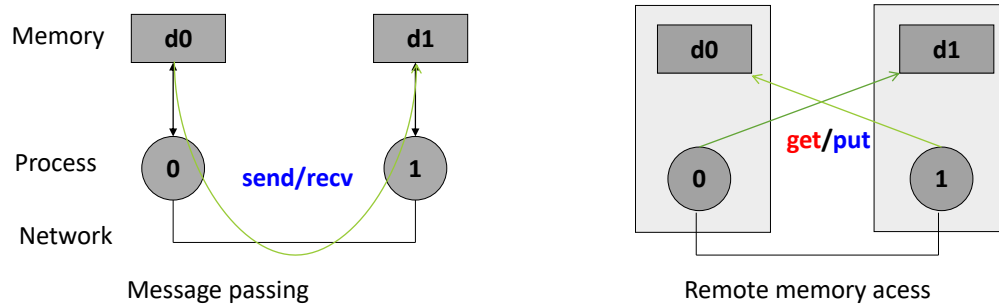
MPI - MPI Programming Model

- Distributed memory API



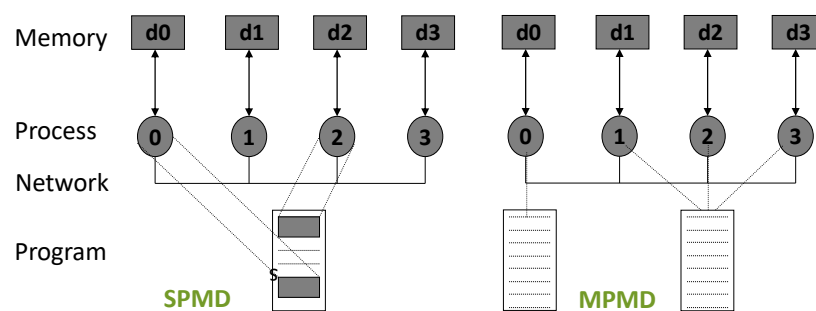
MPI - MPI Programming Model

- Communication model
 - Message passing (two sides operation)
 - Remote memory access (one side operation)



MPI - MPI Programming Model

- SPMD or MPMD
 - Single / Multiple Program Multiple Data
 - Data distributed over processes
 - Communication between processes via network



MPI – Message passing library

- Include:
 - Environment management routines
 - Point to point communication to use with C, C++, Fortran
 - Datatypes management
 - Collective communications
 - Groups of process and communicators
 - Process topologies
 - Parallel I/O, RMA, dynamic process (MPI-2)
 - Non-blocking collective communication, RMA improvement, parallel programming environment (MPI-3)

References

- W. Gropp, E. Lusk and A. Skjellum, Using MPI: Portable Parallel Programming with the Message-Passing Interface, 3rd edition, The MIT Press, 2014.
- W. Gropp, E. Lusk and R. Thakur, Using Advanced MPI: Modern Features of the Message-Passing Interface, The MIT Press, 2014.
- <https://www.open-mpi.org/>
- http://www.idris.fr/data/cours/parallel/mpi/choix_doc.html
- P. Pacheco, M. Malensek, An Introduction to Parallel Programming, Elsevier Science, 2nd ed., 2019.
- B. Barney, Introduction to Parallel Computing, https://computing.llnl.gov/tutorials/parallel_comp, consulted on Nov. 2018.
- V. Eijkhout, Introduction to High-Performance Computing, <http://pages.tacc.utexas.edu/~eijkhout/istc/istc.html>, consulted on Nov. 2018.

MPI - Environment Management Routines

- hello_mpi.c

```
#include <stdio.h>
#include "mpi.h"

int main(int argc, char **argv)
{
    int myrank, nbprocs;

    MPI_Init( &argc, &argv );
    MPI_Comm_rank( MPI_COMM_WORLD, &myrank );
    MPI_Comm_size( MPI_COMM_WORLD, &nbprocs);

    printf( " Hello from proc. %d/%d\n ",
            myrank, nbprocs);

    MPI_Finalize();
    return 0;
}
```

MPI's header file

Execution environment initialization

End of MPI execution

MPI – Compiling and running MPI applications

- Compiling

```
$ mpicc hello_mpi.c -o hello_mpi
```

- Running

```
$ sbatch submit_hello_mpi.sh
```

```
#!/bin/bash
# submit_hello_mpi.sh script d'execution
#SBATCH --partition=court      # partition 'court' pour execution
#SBATCH --ntasks=8             # 8 tasks
#SBATCH --ntasks-per-core=1    # 1 task par core
#SBATCH --job-name=hello_mpi

#execution
mpiexec ./hello_mpi
```

MPI – Get processor information

```
#include <stdio.h>
#include "mpi.h"
#include <sched.h>

int main(int argc, char **argv)
{
    int rang=-1, nbProcs=0, nameLength=0;
    int cpuId=-1; /* Numero du core du nœud utilise */
    char proc_name[MPI_MAX_PROCESSOR_NAME]; /* Nom du nœud utilise */

    MPI_Init( &argc, &argv );
    MPI_Comm_rank( MPI_COMM_WORLD, &rang );
    MPI_Comm_size( MPI_COMM_WORLD, &nbProcs );

    MPI_Get_processor_name( proc_name, &nameLength );
    cpuID = sched_getcpu();
    printf( " Hello from proc. %d/%d on CPU %d of %s\n ",
           rang, nbProcs, cpuID, proc_name );

    MPI_Finalize(); return 0;
}
```

MPI - Environment Management Routines

- `MPI_Get_processor_name`: return the processor name and its length
`int MPI_Get_processor_name(char *name, int resultlength);`
- `MPI_Wtime`: return an elapsed wall clock time in seconds
`double MPI_Wtime(void);`
- `MPI_Abort`: terminates all process of communicator if exception: ex. malloc
`int MPI_Abort(MPI_Comm comm, int errorcode);`

MPI – Point-to-point communication

```
#include <stdio.h>
#include "mpi.h "

int main(int argc, char **argv)
{
    int          myrank, nbprocs, tag=50, tag2=60, nameLength;
    MPI_Status status;
    float        ts[2]={1.0, 2.0}, tr[2]={-1.0, -1.0};

    MPI_Init( &argc, &argv );
    MPI_Comm_rank( MPI_COMM_WORLD, &myrank );
    MPI_Comm_size( MPI_COMM_WORLD, &nbprocs);

    ts[0] = ts[0]+ts[1]*myrank;
```

MPI – Point-to-point communication

```

if (myrank == 0) {
    MPI_Send( ts, 1, MPI_FLOAT, 1, tag, MPI_COMM_WORLD );
    MPI_Recv( tr, 1, MPI_FLOAT, 1, tag2, MPI_COMM_WORLD, &status );

    printf(" Proc %d: sent data %f, received data %f\n ", myrank, ts[0], tr[0]);
}
else if (myrank == 1) {
    MPI_Recv( tr, 1, MPI_FLOAT, 0, tag, MPI_COMM_WORLD, &status );
    MPI_Send( ts, 1, MPI_FLOAT, 0, tag2, MPI_COMM_WORLD );

    printf(" Proc %d: sent data %f, received data %f\n ", myrank, ts[0], tr[0]);
}

MPI_Finalize();
return 0;
}

```

Dead lock!

MPI – All-to-one

```

#include <stdio.h>
#include <string.h>
#include "mpi.h "

int main(int argc, char **argv)
{
    int          myrank, nbprocs, cpuid=-1, src, tag=50, nameLength;
    MPI_Status status;
    char         message[100], procName[MPI_MAX_PROCESSOR_NAME];

    MPI_Init( &argc, &argv );
    MPI_Comm_rank( MPI_COMM_WORLD, &myrank );
    MPI_Comm_size( MPI_COMM_WORLD, &nbprocs);
    MPI_Get_processor_name(procName, &nameLength);
    cpuid = sched_getcpu();
}

```

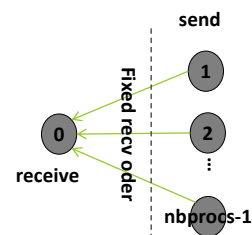
MPI – All-to-one

```

if ( myrank != 0 ) {
    sprintf( message, "Hello from %d on %s-cpu%d!" , myrank, procName, cpuid );
    MPI_Send( message, strlen(message)+1, MPI_CHAR,
              0, tag, MPI_COMM_WORLD ); }
else
    for ( src=1; src<nbprocs; src++ ) {
        MPI_Recv( message, 100, MPI_CHAR, src,
                  tag, MPI_COMM_WORLD, &status );
        printf( "%s\n", message );
    }

MPI_Finalize();
return 0;
}

```



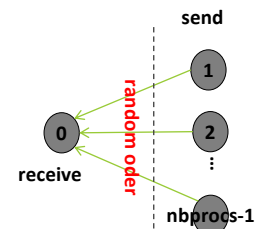
MPI – All-to-one

```

if ( myrank != 0 ) {
    sprintf( message, "Hello from %d on %s-cpu%d!" , myrank, procName, cpuid );
    MPI_Send( message, strlen(message)+1, MPI_CHAR,
              0, tag, MPI_COMM_WORLD ); }
else
    for ( src=1; src<nbprocs; src++ ) {
        MPI_Recv( message, 100, MPI_CHAR, MPI_ANY_SOURCE,
                  tag, MPI_COMM_WORLD, &status );
        printf( "%s\n", message );
    }

MPI_Finalize();
return 0;
}

```



MPI – Point-to-point communication

- Two side operation
 - A Send must be matched by a Recv
- Safe program in blocking communication

```
MPI_Comm_rank (MPI_COMM_WORLD, myrank);
if (myrank == 0) {
    MPI_Send( sendbuf, count, MPI_INT, 1, tag1, MPI_COMM_WORLD );
    MPI_Recv( recvbuf, count, MPI_INT, 1,
              tag2, MPI_COMM_WORLD, &status );
}
else if (myrank == 1) {
    MPI_Recv( recvbuf, count, MPI_INT, 0,
              tag1, MPI_COMM_WORLD, &status );
    MPI_Send( sendbuf, count, MPI_INT, 0, tag2, MPI_COMM_WORLD );
}
```

MPI – Blocking communication

- Features
 - Completion of `MPI_Send` means send variable can be reused
 - Completion of `MPI_Recv` mean receive variable can be read
 - Cause synchronization -> Increase communication time
 - Affect the performance of parallel program
- Solution
 - Non-blocking communication

MPI – Non-blocking communication

- Operation in 2 steps

- Request: MPI_Isend, MPI_Irecv

```
MPI_Isend(&buf, count, datatype, dest, tag, comm, &request);
```

```
MPI_Irecv(&buf, count, datatype, src, tag, comm, &request);
```

- Completion: MPI_WAIT(&request, &status);

- Test of completion:

```
MPI_TEST(&request, &flag, &status);
```

- Avoid dead lock

- Allow communication / computation overlapping

- Persistent request can be used if many communication

MPI – Non-blocking communication

- Example

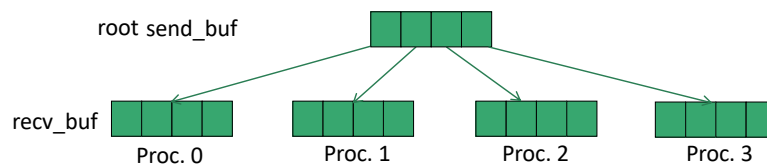
```
MPI_Comm_rank (MPI_COMM_WORLD, myrank);
if (myrank == 0) {
    MPI_Isend( sendbuf, count, MPI_INT, 1,
               tag, MPI_COMM_WORLD, &request0 );
    MPI_Recv( recvbuf, count, MPI_INT, 1,
               tag, MPI_COMM_WORLD, &status );
    /* or MPI_Irecv + MPI_Wait */
}
else if (myrank == 1) {
    MPI_Isend( sendbuf, count, MPI_INT, 0,
               tag, MPI_COMM_WORLD, &request1 );
    MPI_Recv( recvbuf, count, MPI_INT, 0,
               tag, MPI_COMM_WORLD, &status );
    /* or MPI_Irecv + MPI_Wait */
}
```

MPI – Collective communication

- What is it?
 - Communication involving all processes of a group
- Objective
 - Increase the performance of parallel program
- How?
 - By reduce of idle processes, decrease the communication time
- Use cases
 - When I/O
 - Parallel algorithms need collective communication

MPI – Collective communication

- Broadcast
 - A process (`root`) has a message to send to others

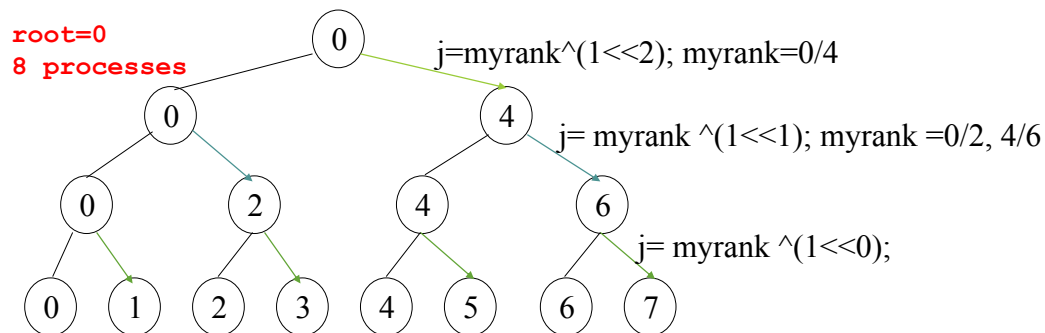


```
int MPI_Bcast(void *msg, int count,
             MPI_Datatype datatype, int root, MPI_Comm comm);
```


MPI – Collective communication

- Broadcast

- Possible implementation:



MPI – Collective communication

- Broadcast - Broadcast of the dimension of a image

```
int myrank, size, dims[2], i, tag=30;
MPI_Comm_rank( MPI_COMM_WORLD, &myrank );
MPI_Comm_size( MPI_COMM_WORLD, &nbprocs );

if (myrank == 0){
    /* Fill dims */
    for ( i=1; i<size; i++)
        MPI_Send( dims, 2, MPI_INT, i, tag, MPI_COMM_WORLD );
}
else
    MPI_Recv(dims, 2, MPI_INT, 0, tag, MPI_COMM_WORLD);
```

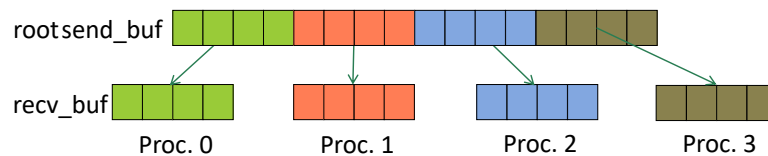
Point to point communication:
Steps - $O(\text{nbprocs})$

```
MPI_Bcast(dims, 2, MPI_INT, 0, MPI_COMM_WORLD);
```

Collective communication:
Steps - $O(\log_2(\text{nbproces}))$
with binary tree

MPI – Collective communication

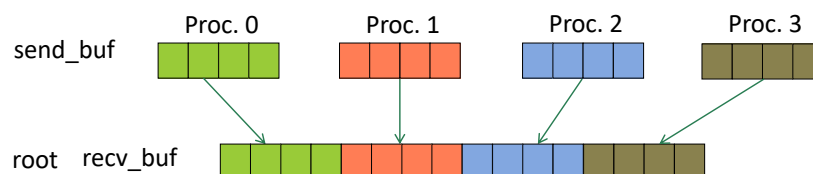
- Scatter – Data distribution



```
int MPI_Scatter( void *sendbuf, int sendcnt,
                MPI_Datatype sendtype, void *recvbuf,
                int recvcnt, MPI_Datatype recvtype,
                int root, MPI_Comm comm );
```

MPI – Collective communication

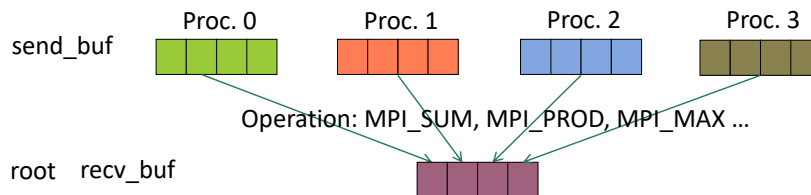
- Gather - The processes of a group have data to merge together



```
int MPI_Gather( void *sendbuf, int sendcnt,
               MPI_Datatype sendtype, void *recvbuf,
               int recvcnt, MPI_Datatype recvtype,
               int root, MPI_Comm comm );
```

MPI – Collective communication

- Reduce – Gather + operation on data

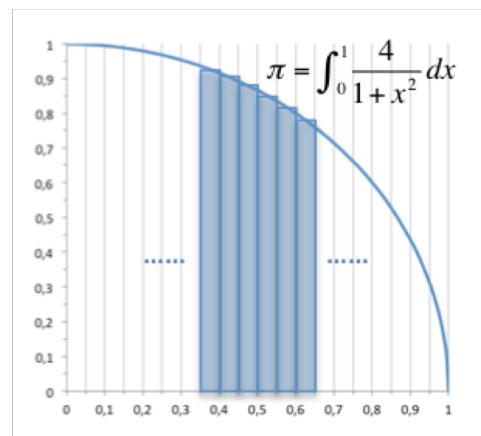


```
int MPI_Reduce( void *operand, void *result,
                int count, MPI_Datatype datatype, MPI_Op op,
                int root, MPI_Comm comm );
```

MPI – Exercice – Computing Pi

```
#include <stdio.h>

int main(int argc, char **argv)
{
    long nb_rectangles=1000000, i;
    double x, pas;
    double sum=0.0, pi=0.0;
    pas = 1.0 / nb_rectangles ;
    for (i=0; i<nb_rectangles; i++) {
        x = (i+0.5)*pas;
        sum += 4.0 / (1.0 + x*x);
    }
    pi = pas * sum ;
    printf("Pi=%f\n", pi) ;
    return 0;
}
```



47

MPI – Exercice – Computing Pi

```
#include <stdio.h>
#include <mpi.h>

int main(int argc, char **argv)
{
    long    i, nb_rectangles=0, deb=0, fin=0, rects_par_proc=0;
    double  x, pas, sum=0.0, pi=0.0;
    int     myrank, nbprocs;

    MPI_Init( &argc, &argv );
    MPI_Comm_rank( MPI_COMM_WORLD, &myrank );
    MPI_Comm_size( MPI_COMM_WORLD, &nbprocs);

    if (myrank==0) nb_rectangles=1000000;

    MPI_Bcast(&nb_rectangles, 1, MPI_INT, 0, MPI_COMM_WORLD);
```

48

MPI – Exercice – Computing Pi

```
    pas = 1.0 / nb_rectangles ;
    rects_par_proc=nb_rectangles / nbprocs;
    deb=myrank*rects_par_proc;
    fin=deb+rects_par_proc;

    for (i=deb; i<fin; i++) {
        x = (i+0.5)*pas;
        sum += 4.0 / (1.0 + x*x);
    }
    sum = pas * sum ;

    MPI_Reduce(&sum, &pi, 1, MPI_DOUBLE, MPI_SUM, 0, MPI_COMM_WORLD);

    if (myrank==0) printf("Pi=%0.121f\n", pi);
    MPI_Finalize();
    return 0;
}
```

MPI – Collective communication

- Barrier synchronization
 - Make a appointment for all processes
- Use case: time measurement
 - Time measurement for each process

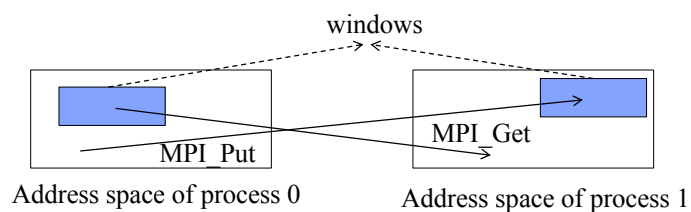
```
double start, proc_exetime;
MPI_Barrier(MPI_COMM_WORLD);
start = MPI_Wtime();
.....
proc_exetime= MPI_Wtime()- start;
```

In main function

- Execution time of program: the one of the slowest process

MPI – RMA (Remote Memory Access)

- Direct access by one process to parts of the memory of another process
- Software implementation
 - Process 0 put data into process 1's data window
 - Process 1 get data from process 0's data window



MPI – RMA (Remote Memory Access)

- Procedure
 - RMA window creation: example with `MPI_Win_Create`
 - Process synchronization: example `MPI_Fence`
 - RMA operations: `MPI_Get`, `MPI_Put`, `MPI_Accumulate`
 - RMA window free: `MPI_Win_free`
- Characteristics
 - Public memory creation
 - Collective operation
 - One process create the window, accessible by all processes

MPI – Exercice – Computing Pi

```
#include <stdio.h>
#include <mpi.h>

int main(int argc, char **argv)
{
    long    i, n=0, rects_par_proc=0, deb=0, fin=0;
    double x, pas, sum=0.0, pi=0.0;
    int     myrank, nbprocs;
    MPI_Win win_pi, win_n;

    MPI_Init( &argc, &argv );
    MPI_Comm_rank( MPI_COMM_WORLD, &myrank );
    MPI_Comm_size( MPI_COMM_WORLD, &nbprocs);

    if (myrank==0) n=1000000;
```

MPI – Exercice – Computing Pi

```

if (myrank==0) {
    MPI_Win_create(&n, sizeof(long), sizeof(long),
        MPI_INFO_NULL, MPI_COMM_WORLD, &win_n);
    MPI_Win_create(&pi, sizeof(double), sizeof(double),
        MPI_INFO_NULL, MPI_COMM_WORLD, &win_pi);
}
else {
    MPI_Win_create(MPI_BOTTOM, 0, sizeof(long),
        MPI_INFO_NULL, MPI_COMM_WORLD, &win_n);
    MPI_Win_create(MPI_BOTTOM, 0, sizeof(double),
        MPI_INFO_NULL, MPI_COMM_WORLD, &win_pi);
}

MPI_Win_fence(0, win_n);
if (myrank != 0) MPI_Get(&n, 1, MPI_LONG, 0, 0, 1, MPI_LONG, win_n);
MPI_Win_fence(0, win_n);

```

MPI – Exercice – Computing Pi

```

pas = 1.0 / n ;
rects_par_proc = n / nbprocs;
deb = myrank*rects_par_proc;
fin = deb+rects_par_proc;
for (i=deb; i<fin; i++) {
    x = (i+0.5)*pas;    sum += 4.0 / (1.0 + x*x);
}
pi = pas * sum ;
MPI_Win_fence(0, win_pi);
if (myrank)
    MPI_Accumulate(&pi, 1, MPI_DOUBLE, 0, 0, 1, MPI_DOUBLE, MPI_SUM, win_pi);
MPI_Win_fence(0, win_pi);
if (myrank==0) printf("Pi=%0.121f\n", pi);
MPI_Finalize(); return 0;
}

```

Parallel computing – Performance evaluation

- Sequential program: user CPU usage time

```
#include <sys/resource.h>
#include <time.h>
#include <stdio.h>

int main() {
    struct rusage ru;
    struct timeval tim;
    double total; int i;

    for (i=0; i<10000000; i++) {};
    getrusage(RUSAGE_SELF, &ru);
    tim = ru.ru_utime;
    total = (double)tim.tv_sec + (double)tim.tv_usec/1000000;

    printf("Total time taken by CPU : %f\n", total);
    return 0;
}
```

Parallel computing – Performance evaluation

- MPI program

- Execution time

- Time for computation
 - Time for communication
 - Time for processes synchronization & management

- Execution time measurement: **Wall clock time**

- Time elapsed between the end and the beginning of a program

Parallel computing – Performance evaluation

- Comparison with sequential program
 - Make a appointment for all processes
- Metrics
 - Speedup
 - Efficiency
 - Scalability
 - Redundancy
- Laws
 - Amdahl's laws
 - Gustafson-Barsis law
 - ...

Parallel computing – Performance evaluation

• Second law of Amdhal

- Speedup

$$S_N(M) = \frac{T_1(M)}{T_N(M)} \leq N$$

Sequential execution of the parallel program
The best sequential algorithm?

N: processes number; M: problem size

- Efficiency $E_N(M) = \frac{S_N(M)}{N}$

• Gustafson-Barsis law

$$S(N) = N - \alpha(N-1); \quad \alpha = a/(a+b)$$

a+b: execution time of the parallel program
with P processes
a: sequential part; b: parallel part

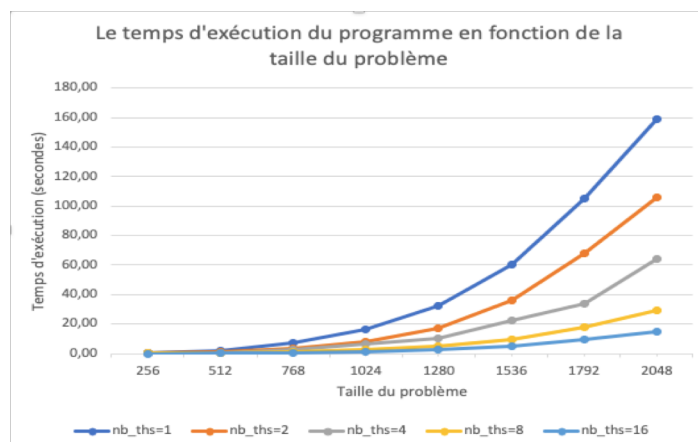
Parallel computing – Performance evaluation

- Example of a openMP program – execution time

Nb_threads Taille	1	2	4	8	16
256	0,22	0,16	0,13	0,06	0,03
512	1,88	1,19	0,77	0,36	0,18
768	7,09	3,71	2,64	1,02	0,57
1024	16,29	8,24	6,35	2,36	1,27
1280	31,92	17,33	10,60	4,72	2,58
1536	60,50	36,28	22,07	9,52	5,01
1792	105,13	67,82	33,59	17,83	9,33
2048	158,88	105,99	64,40	28,90	15,17

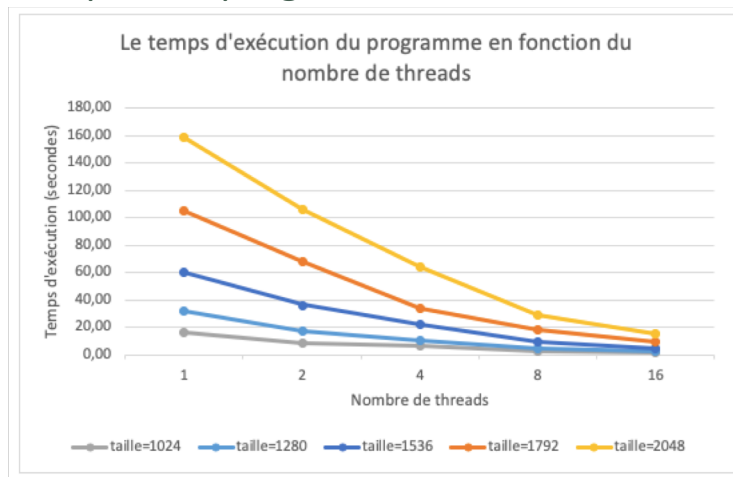
Parallel computing – Performance evaluation

- Example of a openMP program – execution time



Parallel computing – Performance evaluation

- Example of a openMP program – execution time



Parallel computing – Performance evaluation

- Example of a openMP program - Speedup

Nb_threads Taille	1	2	4	8	16
512	1	1,58	2,43	5,15	10,21
1024	1	1,98	2,57	6,89	12,83
1536	1	1,67	2,74	6,36	12,08
2048	1	1,50	2,47	5,50	10,47

Parallel computing – Performance evaluation

- Example of a openMP program - Speedup

